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## Evaluation of Collapse Characteristics with Respect to Aspect Ratio of Cross-Section for Thin-Walled Structures with Curved Shape Using Finite Element Limit Analysis

\*, \*\*, Keepoong Kim, Hyunsup Kim, Hoon Huh

## **ABSTRACT**

This paper is concerned with collapse characteristics and an energy absorption capacity for thin-walled structures with curved shape with respect to aspect ratio of cross-section. The energy absorption capacity influence on yield strength and geometric shape such that shape of cross-section and thickness. S-rails with several aspect ratio of rectangle cross-section are selected for thin-walled structures with curved shape. The analysis of an S-rail has been carried out using finite element analysis for evaluation of collapse characteristics. For collapse analysis of an S-rail, a limit analysis formulation with shell element has been derived and a contact scheme has been considered. Collapse analysis has been carried out for an S-rail with several rectangle cross-section and the energy absorption ratio with respect to aspect ratio of cross-section is calculated. From this result, references for fundamental design have been shown for thin-walled structures with curved shape.

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: Finite Element Limit Analysis(
                                                                                     (Side Rail),
                                                                                                   Collapse
                                                                    ),
                 Behavior Analysis(
                                                   ), Energy Absorption Ratio(
                                                                                              )
                                                                       (side rail)
1.
                                                         (front side member)
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                                                                                          가
         가
                                                                          Abramowicz 1)
                                                           Wierzbicki
                                                                              (folding mechanism)
                                                                                                    . Reid 2)
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.2-3)
                                                                                                                                                                             , Hölder
                                                                                                                                                                                                                                                .3)
                                                                                                    가
                                                                                                                                         minimize \tilde{q}(\mathbf{u})
                                                                                                                                         subject to \widetilde{q} = \overline{\sigma} \int_{D} \left\| \mathbf{\epsilon} \right\|_{(-\nu)} \mathrm{d}\Omega
                                                                                                                                                                  \int_{\partial D_s} \mathbf{t} \cdot \mathbf{u} \, \mathrm{d} \Gamma = 1
                                                                                                                                                                                                                                                 (2)
                                                                                                                                                                  Tr(\mathbf{\varepsilon}) = 0
                        가
                                                                     가
                                                                                                                                                                   kinematic boundary conditions
                                                                                                                                                                   \bar{\sigma}
                                                                                                                                                                                                                                                     가
                                                                                                가
                                                                                                                                                                                                  (bisection method)
                                                                                                                                        \overline{\sigma}^{(k+1)} = \frac{\overline{\sigma}^{(k)} + \overline{\sigma}_o}{2}
                                                                                                                                                                                                                                                  (3)
                                                                                                                                                               \overline{\sigma} = H\left(\overline{\varepsilon}^{p}\right) \qquad H\left(\overline{\varepsilon}^{p}\right)
\overline{\varepsilon}^{p}
                                                                .5)
2.
                                                                                                                                                         (flow stress)
                                                                                                                                         \overline{\sigma} = \sigma_o \left( 1 + A \overline{\varepsilon}^p \right)^n
                                                                                                                                                                                                                                                  (4)
                                                                                                                                                    , A n
                                                                                                                                                \sigma_{\scriptscriptstyle o}
                                                                                                                                                 (2)
     maximize q(\sigma)
     subject to \nabla \cdot \boldsymbol{\sigma} = 0 in D
                                                                                                             (1)
                             \boldsymbol{\sigma} \cdot \mathbf{n} = q \mathbf{t} on \partial D_s
                             \|\boldsymbol{\sigma}\|_{(v)} \le \sigma_o in D
                                                                                                                                                                                 . 4-5)
                             \sigma
                                                                                                                                                               가
                                                                                                                                   3.
                               \partial D_S
                                                                                                q
                                    , \|\ \|_{(v)} von-Mises norm
                                                                                                                                                                                                                             가
                                                                               (duality theorem)
                                                                                                                                                                                                                         S-rail
                                                                                                                                                                            . S-rail
                                                                                                                                                                                                                                            Fig. 1
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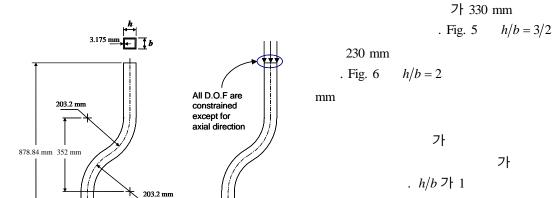
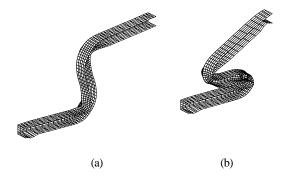


Fig. 1 Geometry and boundary conditions of an S-rail

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Table 1 Aspect ratio of rectangle cross-section and dimension of S-rails for collapse analysis

	h/b	b (mm)	h (mm)
Model I	1/2	84.7	42.3
Model II	2/3	76.2	50.8
Model III	1	63.5	63.5
Model IV	3/2	50.8	76.2
Model V	2	42.3	84.7



. Fig. 4 h/b = 1

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, 1

Fig. 2 Deformed shapes of an S-rail with aspect ratio h/b of rectangle cross-section = 1/2: (a) displacement at the end = 200 mm; (b) displacement at the end = 450 mm

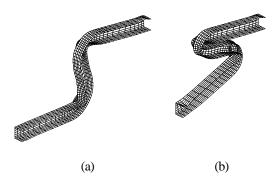


Fig. 3 Deformed shapes of an S-rail with aspect ratio h/b of rectangle cross-section = 2/3: (a) displacement at the end = 200 mm; (b) displacement at the end = 450 mm

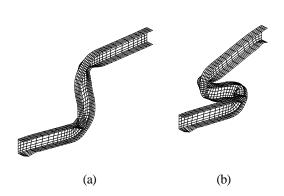


Fig. 4 Deformed shapes of an S-rail with aspect ratio *h/b* of rectangle cross-section = 1 (a) displacement at the end = 200 mm; (b) displacement at the end = 450 mm

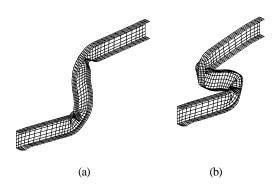


Fig. 5 Deformed shapes of an S-rail with aspect ratio h/b of rectangle cross-section = 3/2: (a) displacement at the end = 200 mm; (b) displacement at the end = 450 mm

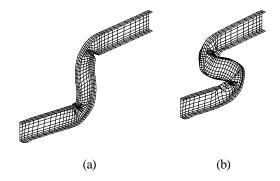
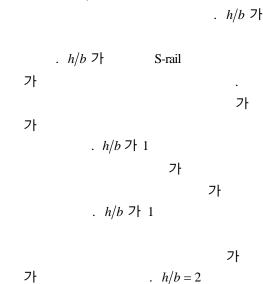


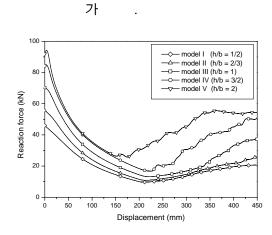
Fig. 6 Deformed shapes of an S-rail with aspect ratio h/b of rectangle cross-section = 2: (a) displacement at the end = 200 mm; (b) displacement at the end = 450 mm

S-rail

Fig. 7

h/b





150mm

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Fig. 7 Collapse load of S-rails with respect to displacement

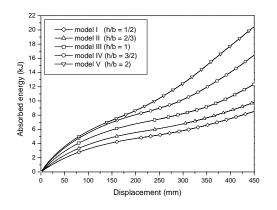


Fig. 8 Absorbed energy to S-rails with respect to displacement

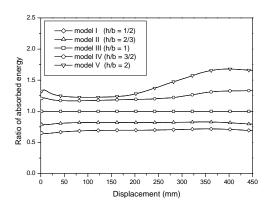


Fig. 9 Ratio of absorbed energy to S-rails with respect to displacement

가 . , S-rail 가 가 . . Fig. 9 
$$h/b=1$$

. 
$$h/b$$
 S-rail

. Fig. 10

200 mm 400 mm

 $h/b$ 

. Fig. 10(a) 200 mm

 $h/b$ 

2 200 mm

 $h/b$ 

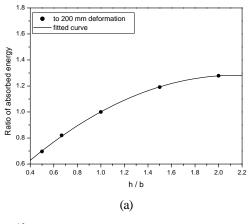
. Fig. 10(b) 400

mm

 $h/b$ 

. Fig. 10

Table. 2 
$$E_R = C_0 + C_1 \left(\frac{h}{b}\right) + C_2 \left(\frac{h}{b}\right)^2 \tag{5}$$



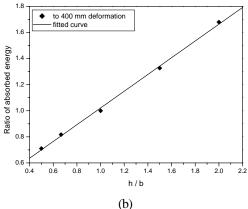


Fig. 10 Ratio of absorbed energy to S-rails with respect to aspect ratio h/b of rectangle cross-section: (a) to 200 mm deformation at the end; (b) to 400 mm deformation at the end

Table 2 Coefficient in approximation of the energy absorption ratio with respect to aspect ratio *h/b* of rectangle cross-section

	$C_0$	$C_1$	$C_2$
To 200 mm deformation	0.2933	0.9236	-0.2157
To 400 mm deformation	0.3789	0.6422	0

4.

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S-rail , 가

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